



Mass Flow Meter

Model
NIMS 1200

Product Manual



www.nipponinstruments.com

Features

- ò Low pressure drop
- ò Flow range: +/- 200 slm (bidirectional)
- ò Accuracy 1.5% m.v. (typical)
- ò Very fast update time
- ò Fully calibrated & temperature compensated
- ò Low zero drift

Product Summary

The **NIMS 1200** sensor is ACT digital flow meter offered specifically for ventilator applications. It measures the flow rate of air, oxygen and other non-aggressive gases with superb accuracy. A special design of the flow channel results in very low pressure drop through the body of the sensor making it extremely suitable for very demanding application, such as medical ventilation and respiratory applications. The **NIMS 1200** operates from a 5 V supply voltage and features digital I²C interface. The measurement results are internally linearized & temperature compensated.

The outstanding performance of this sensor is based on sensor technology, which combines a thermal sensor chip and a high-performance

integrated 24-bit AD acquisition CMOS microprocessor. The flow rate of the gas is measured by a thermal sensor element which assures very fast signal processing time and bidirectional measurement with best-in-class accuracy.

Applications

Medical^ Process automation^ Burner control^ Fuel cell control^ Spectroscopy^ Environment monitoring^ Laboratory

OEM industry customization and solutions

Our company is committed to research and development of various sensors, with professional R&D laboratories and equipment, supporting a variety of simulation environment experimental conditions, to create high-quality product production and inspection process. The **NIMS 1200** is one of the chips independently developed and manufactured by our company. The flow range and independent flow channel structure can be customized according to the application site and customer needs. ACT professionally provide customers with complete application solutions

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1. Sensor performance

Table 1 **NIMS 1200** performance table of accuracy conditions¹

| Parameter | Condition | Value | | Unit |
|--|------------------------------------|------------------------|-------|-----------------------|
| Flow Ranges | Air/N ₂ /O ₂ | -200~+200 ² | | slm ³ |
| | | Max. | Typ. | |
| Accuracy ^{4 5 6 7} | span | ±2.5 | ±1.5 | % m.v. |
| | offset | ±0.1 | ±0.05 | slm |
| Repeatability ^{4 7} | span | ±1 | ±0.5 | % m.v. |
| | offset | ±0.05 | ±0.02 | slm |
| Noise Level ^{4 7} | span | ±1 | ±0.5 | % m.v. |
| | offset | ±0.1 | ±0.05 | slm |
| Accuracy Shift Due to Temperature Variation ⁸ | span | ±0.75 | ±0.25 | % m.v./10d° |
| | offset | ±0.0 | ±0.0 | slm |
| Position sensitivity | non-horizontal position | <0.05 | | slm |
| Pressure Drop | @60slm | <100/<0.4 | | Pa/inH ₂ O |
| | @200slm | <600/<2.4 | | |

Table2 Media compatibility and materials

| Parameter | Value |
|------------------------|---|
| Calibration | Air N ₂ O ₂ |
| Media Compatibility | Air (non-condensing), N ₂ , O ₂ , non- aggressive gases |
| Wetted Materials | PPE+PS blend (medical grade: biocompatible; ISO 10993 or USP Class VI), Si, Si ₃ N ₄ , SiO _x , Gold, Epoxy, Polyurethane, stainless steel (annealed) |
| RoHS REACH | RoHS and REACH compliant |
| Sensor Weight with Cap | <25 gram |

1 Unless otherwise noted, all sensor specifications are valid at 25°C with Vdd = 5V and absolute pressure = 966 mbar.

2 The range of **NIMS 1200-200** models is ±200slm, other models are shown in Table 10.

3 In standard liter per minute at 20°C and 1013 mbar

4 With ideal inlet and outlet conditions, at VDD = 5V, 25°C, absolute pressure = 966 mbar

5 Including offset, non-linearity, hysteresis

6 Sensor position horizontal (see Section 8.1)

7 Span or offset value, whichever is larger

8 Shift due to temperature variation compared to calibration temperature

2. Sensor electrical characteristics

Electrical characteristics such as sleep power consumption, measurement power consumption, etc., all depend on the power supply. The table 3 details the electrical characteristics of NIMS 1200. If not marked, it means that the power supply voltage is 5V.

Table3 NIMS 1200 electrical characteristics parameter table

| Parameter | Condition | MIN | TYP | MAX | Unit |
|--------------------------------------|--------------------|------|------------------|------|-------|
| Interface | | | I ² C | | |
| Supply Voltage | VDD | 4.75 | 5 | 5.25 | V |
| I ² C Communication Level | High | 4 | - | VDD | V |
| | Low | GND | - | 0.8 | V |
| Sampling Time | | | 10 | | ms |
| Power Consumption | Measure | | 7.5 | 10 | mA |
| I ² C Communication Rate | | | 100 | 400 | Kb/s |
| Operating Temperature | | 0 | | +50 | d' |
| Storage Temperature | | 0 | | +50 | d' |
| Working pressure range | Absolute | 0.7 | | 1.3 | bar |
| Operating Overpressure | Measure | | <u>±0.2</u> | | bar |
| Burst Overpressure | Measure | | >1 | | bar |
| Scale Factor Flow | Air/N ₂ | | 140 | | 1/slm |
| | O ₂ | | 142.8 | | |
| Offset Flow | | | 32000 | | |

3. Sensor communication

NIMS 1200 sensor adopts standard I²C communication protocol to adapt to various devices. The protocol uses two data lines: serial data bus (SDA) and serial time bus (SCL). The two internal data lines have been connected with 4.7K pull-up resistors to VDD. Multiple sensor devices can share the bus; but only one host device can appear on the bus. The sensor I2C address is 0x40, the I2C read command is 0x81, and the I2C write command is 0x80.

If the SCL and SDA signal lines are parallel and very close to each other, it may cause signal crosstalk and communication failure. The solution is to place VDD or GND power signals between the two signal lines, separate the signal lines or use shielded cables. Wait. In addition, it is also possible to improve the integrity of signal transmission by reducing the SCL frequency. The sensor needs to be led out, then a 100nF decoupling capacitor should be added between the positive and negative power supply pins for filtering. This capacitor should be as close as possible to the sensor.

3.1 I²C communication interface characteristics and timing

In the I²C bus, the **NIMS 1200** sensor as a slave device supports a communication rate up to 400kHz bit rate. When the host sends a start signal (low level), the sensor starts to communicate. When the host sends a stop signal (high level), when the communication ends, the start and end signals are only valid when SCL is high.

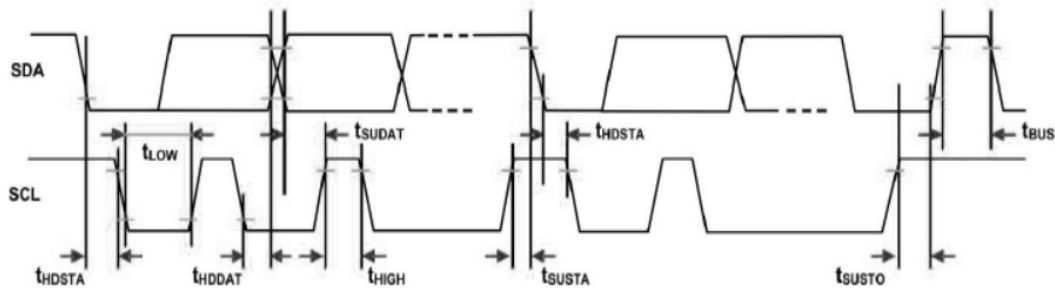


Fig1: I²C Timing

Table4 : I²C parameter

| Parameter | Condition | MIN | TYP | MAX | Unit |
|--|-------------|-----|-----|-----|---------|
| I ² C Clock Frequency | f_{SCL} | 10 | | 400 | KHz |
| Start Signal Time | t_{HDSTA} | 0.8 | | | μs |
| SCL Clock High Width | t_{HIGH} | 0.6 | | | μs |
| SCL Clock Low Width | t_{LOW} | 0.6 | | | μs |
| Set Time Relative to SCL Edge Start Condition | t_{SUSTA} | 0.1 | | | μs |
| Data Retention Time Relative to SCL SDA Edge | t_{HDDAT} | 0.0 | | 0.5 | μs |
| Data Setup Time Relative to SCL SDA Edge | t_{SUDAT} | 1 | | | μs |
| Set Time at SCL Stop Condition | t_{SUSTO} | 0.1 | | | μs |
| Bus Idle Time Between Stop Condition and Start Condition | t_{BUS} | 1 | | | μs |

3.2 Sensor data collection

After the self-test of the **NIMS 1200** sensor, data will be collected in 10 ms cycles. At the end of a measurement cycle, the data output register will be refreshed. Users can collect flow data through flow collection instructions, which are defined as follows:

Table 5 Flow collection command description

| Command | Condition | Hex code | Position | Definition |
|-----------------|--------------|----------|----------|------------------|
| Flow Collection | High Command | 0x10 | Bit15:8 | Sensor data high |
| | Low Command | 0x00 | Bit7:0 | Sensor data low |

3.3 Read device ID

Each **NIMS 1200** sensor has a unique ID with a length of 32 bits, and the device ID query instruction is defined as follows:

Table 6 Device ID query command description

| Command | Condition | Hex code | Position | Definition |
|-----------------|--------------|----------|----------|------------------------------|
| Device ID query | High Command | 0x31 | Bit31:24 | first byte of the ID number |
| | | | Bit23:16 | second byte of the ID number |
| | Low Command | 0xAE | Bit15:8 | third byte of the ID number |
| | | | Bit7:0 | fourth byte of the ID number |

3.4 Reset command

When the user needs to reset the **NIMS 1200** sensor, the software can be reset by sending the following command:

Table 7 Reset command description

| Command | Condition | Hex code |
|---------|--------------|----------|
| Reset | High Command | 0x20 |
| | Low Command | 0x00 |

3.5 **NIMS 1200** I²C command definition

Table 8 I²C protocol frame

| reading sensor frame format: host frame format (SLA+W) + High byte command + Low byte command + (SLA+R) + delay + return data + CRC8 | | |
|--|-----------------|-----------------------------|
| write sensor frame format: host frame format (SLA+W) + High byte command + Low byte command | | |
| :Sensor register list : | | |
| Command description | Command (16bit) | Returns the number of bytes |
| Read traffic | 0 x 1000 | 2 |
| Read ID number | 0 x 31AE | 4 |
| Reset command | 0 x 2000 | NA |

3.6 NIMS 1200 CRC calculation routine

NIMS 1200 sensor CRC verification uses CRC8, the initial value is 0X00, the polynomial is 0x131 ($x^8 + x^5 + x^4 + 1$), please see the code below

```
//*****
// Function name : Calc_CRC8
// Features      : CRC8 calculation initial value 0x00 polynomial 0x131 ( $x^8 + x^5 + x^4 + 1$ )
// Parameter     : u8 *data CRC check the first number u8 Num CRC check data length
// Return        : crc : calculate the value of crc8
//*****
u8 Calc_CRC8(u8 *data, u8 Num)
{
    u8 bit, byte, crc=0x00;
    for(byte=0; byte<Num; byte++)
    {
        crc^=(data[byte]);
        for(bit=8; bit>0; --bit)
        {
            if(crc&0x80) crc=(crc<<1)^0x131;
            else crc=(crc<<1);
        }
    }
    return crc;
}
```

3.7 Flow conversion formula

The flow results need to use the following formula to convert the measured value:

$$\text{Flow [slm]} = \frac{\text{Measurements} - \text{Offset}}{\text{Flow Coefficient}}$$

Example: The offset of NIMS 1200 is 32000, the air flow coefficient is 140, the measured value read by I2C is 33400

$$\text{Flow [slm]} = \frac{33400 - 32000}{140} = 10 \text{ slm}$$

Please note that the first measurement performed directly after chip initialization is invalid.

4. Pin definition

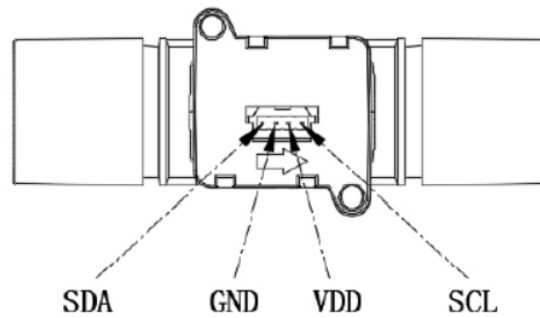


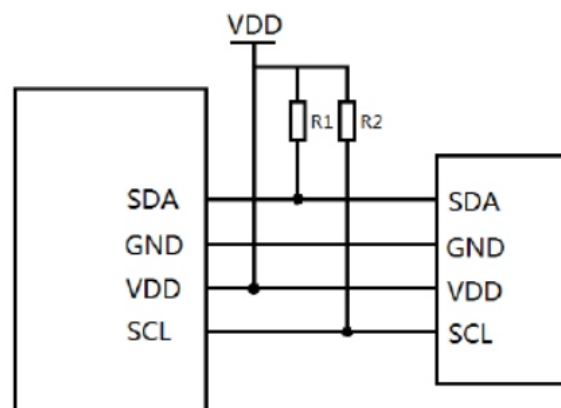
Fig2: Sensor pin layout

Table 9 Pin function description

| Pin | Condition | Type | Description |
|-----|-----------|--------|--|
| 1 | VDD | +5V | power supply pin |
| 2 | SDA | IN/OUT | I ² C digital communication data pin |
| 3 | GND | / | ground |
| 4 | SCL | IN | I ² C digital communication clock pin |

5. Typical circuit

5.1 Typical circuit connection



Note: The recommended resistance value of R1 and R2 is 10K

Fig3: Typical circuit diagram

6. Dimension Unit : mm

6.1 NIMS 1200 dimension

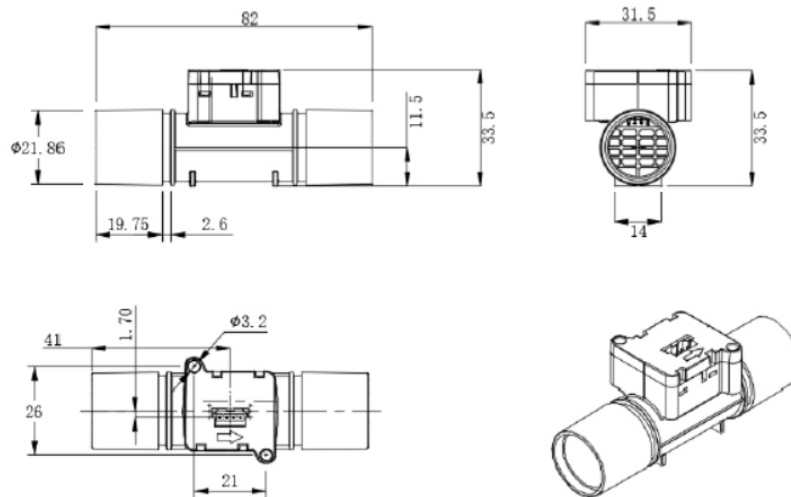
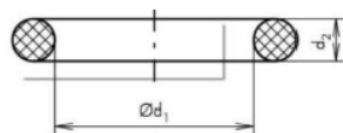


Fig4: Flow sensor dimensions

Note: If the NIMS 1200 sensor is directly soldered on the PCB, it should not be soldered by reflow soldering or soldering, otherwise the sensor may be damaged. During the soldering process, the sensor port must be protected to prevent the solder from splashing and damaging the sensor

6.2 Machinery parts

The accessories of the NIMS 1200 sensor comply with the international standard ISO5356-1: 2004. Detailed information about this type of connection can be found in the standard description. To minimize the risk of accidental disconnection of the connector, a latched connector can be used, or an O-ring can be inserted into the groove, and a pipe with an inner diameter of 23 mm can be connected to the NIMS 1200.



$d_1=19\text{mm}$ $d_2=2\text{mm}$

Section of recommend O-ring

7. Model list

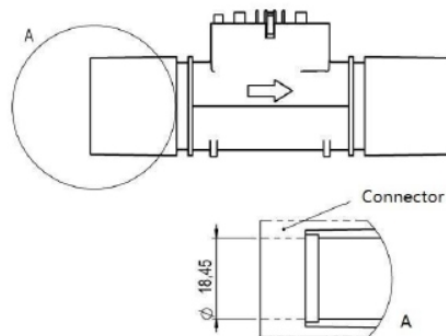
Table10 **Model list**

| Model | Range | Unit |
|---------------|---------|------|
| NIMS-1200-20 | 0 - 20 | slm |
| NIMS-1200-50 | 0 - 50 | slm |
| NIMS-1200-100 | 0 - 100 | slm |
| NIMS-1200-150 | 0 - 150 | slm |
| NIMS-1200-200 | 0 - 200 | slm |

8. Precautions

8.1 Calibration direction

As shown in the figure below, calibrate the sensor horizontally:



8.2 Inlet flow conditions

In order to provide good flow conditions, the inner diameter of the connecting pipe has to be approximately the same as the inner diameter of the **NIMS 1200** main channel. The inlet pipe must be straight and at least 10 cm in length. **NIMS 1200** installed grids at the inlet and outlet of the flow channel to reduce turbulence and improve stability.

8.3 Temperature compensation

NIMS 1200 sensor has digital temperature compensation. The temperature is measured by the on-chip temperature sensor on the chip and then fed back to the sensor processing chip. Therefore, no external temperature compensation is required.

8.4 Processing

The **NIMS 1200** sensor is sturdy and shock resistant. However, the accuracy of the high-precision **NIMS 1200** may be reduced due to improper operation. ACT do not guarantee normal operation in case of improper handling. Note: Avoid any mechanical stress on the solder joints of the sensor during PCB assembly or due to PCB assembly.

8.5 ESD

NIMS 1200 will be exposed to sunlight or strong ultraviolet radiation for a long time, the performance will be reduced, and the casing will be aging.

NIMS 1200 meet the following anti-static standards : -

- AEC-Q-100-002 (4kV HBM)
- AEC-Q-100-003 (200V MM)

Although the sensor meets these specifications, it does not mean that the sensor itself is compatible with ESD. When installing the sensor, please place it in an anti-static tray to prevent electrostatic discharge. In order to avoid damage to the sensor, personnel need to wear an electrostatic bracelet or wear insulated gloves before touching the sensor.

9. Accuracy statement

The **NIMS 1200** sensor is strictly calibrated in accordance with the AS-WI-RD3370 precision measurement guidance document. The performance of the sensor under other test conditions is not guaranteed and cannot be used as part of the sensor performance. Especially for the specific occasions requested by users, no commitment is made.

10. Important notices

1. Do not use this product as safety or emergency stop devices or in any other application where failure of the product could result in personal injury (including death). Do not use this product for applications other than its intended and authorized use. Before installing, handling, using or servicing this product

2. Please consult the datasheet and application notes. Failure to comply with these instructions could result in death or serious injury.

3. Based on the information provided by our suppliers, the materials used in this product and raw materials are harmless to the human body. ACT has not verified this information through third-party analysis.

4. For any application using this product, expressly reject any and all responsibilities, including but not limited to consequential or incidental compensation.